IRB 360 FlexPicker™

Main Applications

Assembly
Material handling
Picking
Packing



Features

- High speed flexibility
- High capacity up to 8 kg payload
- Hygienic design for washdown applications
- Superior tracking performance
- Integrated vision software
- Integrated control of indexing belts

ABB's IRB 360 family of robots, more commonly known as the FlexPicker, can handle payloads of between 1 kg and 8 kg. Each of the family's variants is capable of the fastest picking applications and have been optimized for packing applications. The robot has outstanding motion performance with the shortest cycle times, precision accuracy and high payloads.

Whether operating at high speeds, in narrow or large spaces (maximum 1,600 mm), the IRB 360's stainless steel design allows for easy clean up and sterilization.

A stainless option for food handling applications is IP69K validated so that it can be washed down with industrial detergents and high pressure hot water. This variant is also designed with smooth and easy to rinse-off surfaces and lubricant free joints that are resistant to most corrosives.

Setting up an application becomes easy using PickMaster™ software which has evolved into an invaluable help for integrators and users of IRB 360. It simplifies vision configuration and offers the application tools needed for efficient high speed picking.

The reliable, market leading IRC 5 controller is also an integral part of the FlexPicker robot family. The IRC 5 with TrueMove™ and QuickMove™ guarantees high speeds and path following facilities which allows these robots to track fast moving conveyor belts with extreme accuracy. The IRC 5 also is available in a panel-mounted version that offers substantial space savings and easy integration into machines and production lines.

IRB 360

Specification						
Robot versions		Handlii capaci	Ū	meter	No. Axes	
IRB 360-1/800		1 kg	800) mm	4	
IRB 360-1/1130 *		1 kg	113	30 mm	3/4	
IRB 360-3/1130		3 kg	113	30 mm	3/4	
IRB 360-1/1600		1 kg	160	00 mm	4	
IRB 360-6/1600		6 kg	160	00 mm	4	
IRB 360-8/1130		8 kg	113	30 mm	4	
Supplementary load	d					
on upper arm		350 gram				
on lower arm		350 gram				
Integrated signal supply		12 poles 50V, 250mA				
Integrated vacuum supply		Max. 7 bar/max vacuum 0.75 bar				
* Tested by IPA, all	axes					
Physical						
Robot mounting		Inverted				
Weight		120 kg	120 kg (Standard & Wash-down)			
		145 kg (Stainless Wash-down)				
Performance						
Position repeatibility		0.1 mm	1			
Angular repeatabilit	y					
Standard & stainless axis 4		0.4°				
Wash-down axis 4		1.5°				
Cycle time	0.1 kg	1 kg	3 kg	6kg	8 kg	
25/305/25 (mm)						
IRB 360-1/1130	0.30	0.36				
IRB 360-3/1130	0.40	0.40	0.52			
IRB 360-8/1130		0.38	0.42		0.60	
IRB 360-1/1600	0.35	0.40				
IRB 360-6/1600		0.43	0.48	0,60		
90/400/90 (mm)						
IRB 360-1/1130	0.44	0.51				
IRB 360-3/1130	0.60	0,60	0.75			
		0.55	0.65		0.92	
IRB 360-8/1130		0.00				
IRB 360-8/1130 IRB 360-1/1600	0.50	0.54				

^{*} Cycle times for IRB 360-1/800 differ in cycle time. Please use Robot-Studio or real cycle time tests to verify actual cycle time.

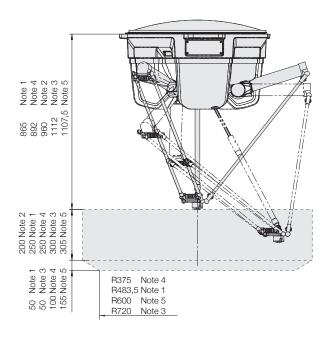
Conveyor tracking**

Constant conveyor	Conveyor speed	
speed [mm/s]	Repeatability [mm]	
200	1.0	
350-750	1.5	
800-1400	5.0	
Start/stop conveyor [mm/s]	Repeatability [mm]	
500 (start/stop in 0.2 sec)	3.5	
Indexing conveyor control	Repeatability [mm]	
3.5 g acceleration/deceleration	2	

^{**} The tracking performance is measured under real conditions with IRB 360-1/1130 and PickMaster. The figures may vary depending on the actual robot max. speed and acceleration performance in relation to what the application demands.

Electrical Connections				
Supply voltage	200-600 V, 60 Hz			
Rated power				
Transformer rating	7.2 kVA			
Power consumption at max load				
Type of Movement	IRB 360/1			
Typical pick - and - place	0.477 kW			
cycle with 1 kg payload				
Environment				
Ambient temperature				
IRB 360 manipulator	±0°C to +45°C			
Relative humidity	Max. 95 %			
Noise level	< 70 dB(A)			
Safety	Double circuits with supervision,			
	emergency stops and safety			
	functions, 3-position			
	enabling device			
Emission	EMC/EMI shielded			
Clean Room options axis 4	Standard - Clean room 7			
	Wash-down- Clean room 5			
	(certified by IPA)			
	Stainless - Clean Room class 5			
	(certified by IPA)			
Option	Collision detection			
Data and dimensions may be chang	ged without notice			

Working range and physical dimensions



Note 1: IRB 360-1/1130 and IRB 360-3/1130

Note 2: IRB 360-1/800 Note 3: IRB 360-1/1600 Note 4: IRB 360-8/1130 Note 5: IRB 360-6/1600

