MOTOMAN ROBOTICS


OPTIONAL EXPLOSION-PROOF

## TOP REASONS TO BUY

■ Motoman Robotics is a global leader with a large install base

- Easy-to-use touch screen teach pendant
- MotoSim ${ }^{\circledR}$ EG simulation software (optional)
- MotoMax 1 warranty (standard)
- Optional intrinsically safe part positioner


COATING•DISPENSING
Payload: 5 kg

## Versatile Coating Robot

- High-speed, versatile six-axis EPX1250 robot is ideal for automotive and other industrial coating applications.
- Offers superior performance and creates smooth, consistent finish with outstanding efficiency for painting and dispensing applications.
- Broadest motion range in its class; proven effective in painting multiple small parts simultaneously, as well as items such as instrument panels and headlamp assemblies.
- Factory Mutual (FM) approved for Class 1, Div. 1 use in hazardous environments.

■ 5 kg (11 lb) payload; 1,256 mm (49.4") horizontal reach; $1,852 \mathrm{~mm}$ (72.9") vertical reach; $\pm 0.15 \mathrm{~mm}( \pm 0.006$ ") repeatability.

■ Highly flexible, compact design; easy to floor, wall or ceiling mount.

- 5 kg payload capacity allows use of air spray gun, electrostatic spray gun or a compact bell gun; providing the ability for higher efficiency and quality of surface coating.
- Structure strength requirement for paint booth reduced due to lightweight design of EPX1250.


## Advanced NX100-FM Controller

- Compact controller reduces installation space by $50 \%$ compared to conventional models.

■ Supports standard networks (such as EtherNet/IP, DeviceNet, ControlNet, Profibus-DP and Interbus-S), enabling connection to paint equipment controllers and production line controllers.

- Includes application-specific software for paint applications.
- Coordinates operation of robot and painting devices, including spray gun.
- Supports gun control instructions such as spray start/stop and painting conditions.
- All painting position parameters can be filed and saved.




## EPX1250 SPECIFICATIONS

| Structure |  | Vertical jointed-arm type |
| :---: | :---: | :---: |
| Controlled Axes |  | 6 |
| Payload |  | 5 kg (11 lb) |
| Vertical Reach |  | 1,852 mm (72.9") |
| Horizontal Reach |  | 1,256 mm (49.4") |
| Repeatability |  | $\pm 0.15 \mathrm{~mm}\left(0.006{ }^{\prime \prime}\right)$ |
| Maximum <br> Motion <br> Range | S-Axis (Turning/Sweep) L-Axis (Lower Arm) U-Axis (Upper Arm) (relative angle of lower arm) R-Axis (Wrist Roll) B-Axis (Bend/Pitch/Yaw) T-Axis (Wrist Twist) | $\begin{aligned} & \pm 170^{\circ} \\ & +120^{\circ}-65^{\circ} \\ & +205^{\circ}-165^{\circ} \\ & \pm 190^{\circ} \\ & \pm 145^{\circ} \\ & \pm 360^{\circ} \end{aligned}$ |
| Maximum Speed | S-Axis L-Axis <br> U-Axis <br> R-Axis <br> B-Axis <br> T-Axis | $185 \%$ 185\% <br> $185^{\circ}$ /s <br> $360^{\circ} / \mathrm{s}$ <br> $410 \% / s^{\circ}$ <br> $500^{\circ}$ s |
| Approximate Mass |  | 110 kg (242.6 lb) |
| Brakes |  | All axes |
| Power Consumption |  | 1.5 kVA |
| Allowable Moment | R-Axis B-Axis T-Axis | $\begin{aligned} & 8.0 \mathrm{~N} \cdot \mathrm{~m} \\ & 8.0 \mathrm{~N} \cdot \mathrm{~m} \\ & 3.0 \mathrm{~N} \cdot \mathrm{~m} \end{aligned}$ |
| Allowable Moment of Inertia | $\begin{aligned} & \text { R-Axis } \\ & \text { B-Axis } \\ & \text { T-Axis } \end{aligned}$ | $\begin{aligned} & 0.20 \mathrm{~kg} \cdot \mathrm{~m}^{2} \\ & 0.20 \mathrm{~kg} \cdot \mathrm{~m}^{2} \\ & 0.07 \mathrm{~kg} \cdot \mathrm{~m}^{2} \end{aligned}$ |
| Mounting |  | Floor, ceiling, wall |

## OPTIONAL PENDANT SPECIFICATIONS

| Dimensions | $235(\mathrm{w}) \times 203(\mathrm{~h}) \times 78(\mathrm{~d})\left(9.25 \mathrm{"} \times 8 \mathrm{8"} \times 3.1^{\prime \prime}\right)$ |
| :--- | :--- |
| Mass | $1.25 \mathrm{~kg}(2.8 \mathrm{lb})$ |
| Material | Reinforced plastics |
| Operation Device | Select keys, axes keys, numerical/application keys, <br> emergency stop button, enable switch |
| Display | 5.7-inch monochrome LCD, backlit white LED, <br> touch panel 320 x 240 pixels (Alphanumeric characters, <br> Chinese characters, Japanese letters, Others) |
| IEC Protection Class | IP54 |
| Cable Length | Standard: 8 m, Optional 20 m <br> Max: 50 m (with optional extension cable) |

NX100-FM CONTROLLER SPECIFICATIONS (WITH STANDARD PENDANT)

| Structure | Free-standing, enclosed type |
| :---: | :---: |
| Dimensions (mm) | 500 (w) x 1400 (h) x 550 (d) (19.7" $\times 55.1^{\prime \prime} \times 21.7{ }^{\prime \prime}$ ) |
| Approximate Mass | 120 kg (264.6 lb) |
| Cooling System | Indirect cooling |
| Ambient Temperature | During operation: $0^{\circ} \mathrm{C}\left(32^{\circ} \mathrm{F}\right)$ to $40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$ During transit and storage: $-10^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right)$ to $+45^{\circ} \mathrm{C}\left(113^{\circ} \mathrm{F}\right)$ |
| Relative Humidity | 90\% max. non-condensing |
| Primary Power Requirements | 3-phase, 240/480/575 VAC at 50/60 Hz |
| Grounding | Grounding resistance: $\leq 100$ ohms Separate ground required |
| Digital I/O NPN-Standard PNP-Optional | Standard I/O: 40 inputs/ 40 outputs consisting of 16 system inputs/16 system outputs, 24 user inputs/24 user outputs Enabled to 1,024 inputs/1,024 outputs |
| Position Feedback | By absolute encoder |
| Drive Units | Servo packs for AC servo motors |
| Accel/Decel | Software servo control |
| Program Memory | 60,000 steps <br> 10,000 ladder instructions |
| Pendant Dim. (mm) | 169 (w) x 314.5 (h) $\times 50$ (d) (6.6" $\times 12.4$ " $\times 2$ ") |
| Pendant Playback Buttons | Teach, Play, Remote, Servo On, Start, Hold, Emergency Stop, Edit Lock (Play Mode Enabled on Controller) |
| Concurrent I/O Ladder | 10,000 Instructions |
| Multi Tasking | Up to 8 concurrent jobs |
| Fieldbus | DeviceNet Master/Slave, AB RIO, Profibus, Interbus-S, M-Net, CC Link, EtherNet IP/Slave |
| Ethernet | 10 Base T/100 Base TX |
| E-Stop | Controlled stop |
| Safety | Dual-channel Emergency Stop Pushbuttons, 3-position Enable Switch, Manual Brake Release <br> Meets ANSI/RIA R15.06-1999 and Canadian safety standards |
| Scavenging Control | Equipped with scavenging control unit for internal pressure explosion-proof manipulator |

